

**INSTALLATION AND OPERATION** 

**USER MANUAL** 

WWW.UNICORE.COM

# **UM220-IV M0**

Industry Grade Multi-GNSS
Positioning Module

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# **Revision History**

Version	Revision	Date
Ver.1.0.0	Primary version	Jun.2018
Ver.1.0.1	Alpha release, Revised Pin definition	Oct.2018
Ver.1.0.2	Revised module size	Dec.2018
Ver.1.0.4	Beta release, aligned with Chinese version 1.0.4	Aug. 2019
R1.1	Chapter 6.2: added shelf life	Sep. 2019
R1.2	Chapter 6.2: revised the MSL instructions Added CE logo	Jan. 2020
R1.3	Added a footnote to elaborate CEP	Oct. 2020
R2	Hardware version 2.3 released, updated the related parameters	Dec. 2020
R2.1	Added the descriptions of SMT stencil	Jun. 2021
R2.2	Updated power supply VCC and V_BCKP; Added different PN information and corresponding solutions to avoid leakage power	Nov. 2021
R2.3	Added notes in Section 4.4	Nov. 2021
R2.4	If hot start is not used, connect V_BCKP to VCC. Revised the VSWR in section 1.2	Nov. 2022
R2.5	Optimized the description of antenna power supply; Added Chapter 4.2 Power Supply Requirements	Apr. 2023
R2.6	Revised Figure 3-1 Mechanical Layout	Oct. 2023
R2.7	Updated Unicore's logo	May 2024
R2.8	Updated the values of symbol C in Table 3-1; Added Table 3-2 Dimensions of the Module with the PN of 2330322000028	Jun. 2024

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# **Foreword**

This document offers you information in the features of the hardware, the installation, specification and use of Unicore UM220-IV M0 product.

#### Readers It Applies to

This document is applied to the technicians who know GNSS Receiver to some extent but not to the general readers.

#### Structure of the Document

This document includes the following:

Introduction: Briefly explaining the functions, performances and installing of the product

Installation: Containing the list of the product package and the details of product

installation

Technical Specification: Offering technical specifications of the product

Hardware Specification: Offering all the information of hardware interface of the product

Module disassembly introduction

Package: Provide packing instructions of UM220-IV M0 modules

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## 1 Introduction

### 1.1 Overview

Unicore UM220-IV M0 is a dual-system GNSS module. It is designed on the basis of Unicore's low power, multisystem, high performance SoC-UFirebird designed. It supports BDS B1+GPS L1 dual-system joint positioning and single system positioning. UM220-IV M0 is compact in size and uses SMT pads to support fully automatic integration of standard discharge and reflow soldering, especially suitable for low cost and low power consumption fields. The radio equipment is in compliance with Directive 2014/53/EU.



Figure 1-1 UM220-IV M0 Module

		Gra	ade		Syste	m	Inter	face	Data Updating Rate
Model	PN	Industry	Automotive	GPS	BDS	GLONASS	UART1	UART2	
UM220-IV M0	2310408000024	•		•	•	•	•		1Hz
UM220-IV M0	2330322000028	•		•	•		•		1Hz

# 1.2 Key Features

Power					
Voltage	+3.0~3.6 VDC				
Power Consumption	90mW				
RF Input					
Input VSWR	≤2.5				
Input Impedance	50Ω				
Antenna Gain	15~30dB				
Physical Characteristics					
Dimensions	10.1*9.7*1.9mm (PN: 2310408000024) 10.1*9.7*2.1mm (PN: 2330322000028)				
Environment					
Operating Temperature	-40°C ~ +85°C				
Storage Temperature	-45°C ~ +90°C				
RoHS	Compliant				
Input/output Data Interface					
UART	1 UART, LVTTL. Baud rate $4800{\sim}115200$ bps				
GNSS Performance					
Frequency	BDS B1: 1561.098MHz GPS L1: 1575.42MHz				
TTFF	Cold Start: 28s  Hot Start: 1s  Reacquisition: 1s  AGNSS <sup>1</sup> : 4s				
Positioning Accuracy <sup>2</sup>	2.0m (dual-system horizontal, open sky) 3.5m (dual-system vertical, open sky)				
Velocity Accuracy (RMS)	0.1m/s (dual-system, Open sky)				
Sensitivity	BDS GPS				

<sup>&</sup>lt;sup>1</sup> Assist date input

<sup>&</sup>lt;sup>2</sup> CEP, 50%



	Tracking	-161dBm	-161dBm
	Acquisition	-146dBm	-147dBm
	Hot start	-154dBm	-155dBm
	Reacquisition	-157dBm	-158dBm
1PPS Accuracy (RMS)	20ns		
Data Updating Rate	1Hz		
Data Output	NMEA 0183, Unic	ore Protocol	

### 1.3 Interface

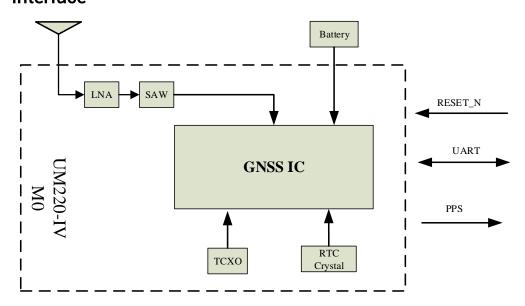


Figure 1-2 Structure Chart

#### **UART**

UM220-IV M0 module supports data transfer and firmware upgrade; the signal input/output level is LVTTL. The default baud rate varies according to the version of firmware, and the baud rate can be configured up to 115200bps<sup>3</sup>.

#### 1PPS

UM220-IV M0 outputs 1PPS with adjustable pulse width and polarity.

<sup>&</sup>lt;sup>3</sup> For more information, see *UFirebird\_Standard Positioning Products Protocol Specification*.

### 2 Product Installation

### 2.1 Installation Preparation

UM220-IV M0 modules are Electrostatic Sensitive Devices and require special precautions when handling.

- Follow the steps in section 2.2 in the correct order.
- ➤ Electrostatic discharge (ESD) may cause damage to the device. All operations mentioned in this chapter should be carried out on an antistatic workbench, wear an antistatic wrist strap and use a conductive foam pad. If an antistatic workbench is not available, wear an antistatic wrist strap and connect the other end to a metal frame to play a role in anti-static.
- ➤ Hold the edge of the module, not in direct contact with the components.
- Please check carefully whether the module has obviously loose or damaged components. If you have questions, please contact us or your local dealer.

Figure 2-1 shows the typical installation of UM220-IV M0 EVK suites.

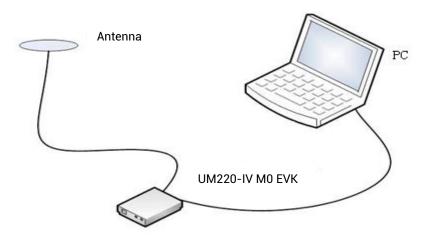


Figure 2-1 Typical Installation of UM220-IV M0 EVK

Please check the contents of the package carefully after receiving the package of UM220-IV M0:

- > UM220-IV M0 EVK suite (with AC Adapter)
- ➤ UM220-IV M0 User manual.
- uSTAR application package.
- Antenna.
- > Antenna connection cable
- Direct serial cable
- ▶ PC



Please keep the box and anti-static plastic bags for storage and handling.

#### 2.2 Hardware Installation

After the above preparations are complete, follow the steps below to install:

- Step 1: Make sure to take full anti-static measures, such as wearing an anti-static wrist strap, grounding the workbench;
- Step 2: Open the UM220-IV M0 evaluation kit;
- Step 3: Select the GNSS antenna with appropriate gain, fix it in the non-block area, using the appropriate cable to connect the antenna to UM220 EVK;
- Step 4: Connect the PC to the EVK serial port through direct serial cable;
- Step 5: Power the evaluation board and initialize the UM220-IV M0;
- Step 6: Open the uSTAR
- Step 7: Controlled the receiver through uSTAR to display constellations view, log messages, and receiver status.

# 3 Technical Specifications

# 3.1 Electrical Specifications

Absolute Maximum Ratings

Item	Pin	Min	Max	Unit	Condition
Power Supply (VCC)	Vcc	-0.5	3.6	V	
VCC Ripple	Vrpp		50	mV	
Digital IO	Vin	-0.5	Vcc +0.2	V	
Storage Temperature	Tstg	-45	90	°C	
MSD (MSL)	□Level 1 □Level 2 ■Level 3 □TBD				

# 3.2 Operation Condition

Item	Pin	Min	Typical Value	Max	Unit	Condition
Power Supply (VCC)	Vcc	3.0	3.3	3.6	٧	
Peak Current	Iccp			53	mA	Vcc=3.0 V
Tracking Average Current	I <sub>ACQ</sub>	29	30	31	mA	Vcc=3.0V
Low Level Input Voltage	Vin_low			0.7	٧	
High Level Input Voltage	Vin_high	1.2			V	
Low Level Output Voltage	Vout_low			0.4	V	lout=-8 mA
High Level Output Voltage	Vout_high	Vcc-0.4			V	lout=8 mA
Antenna Gain	Gant	15		30	dB	
Noise Figure	Nftot		2		dB	
Operation Temperature	Topr	-40		85	°C	



# 3.3 Dimensions

Table 3-1 Dimensions of the Module with the PN of 2310408000024

Symbol	Min (mm)	Typical Value (mm)	Max (mm)
A	9.6	10.1	10.7
В	9.55	9.7	9.85
С	1.8	1.9	2.0
D	0.55	0.65	0.95
E	1.0	1.1	1.2
F	0.5	0.6	0.7
G	0.3	0.4	0.5
Н	0.9	1.0	1.1
М	0.7	0.8	0.9

Table 3-2 Dimensions of the Module with the PN of 2330322000028

Symbol	Min (mm)	Typical Value (mm)	Max (mm)
Α	9.6	10.1	10.7
В	9.55	9.7	9.85
С	2.0	2.1	2.2
D	0.55	0.65	0.95
E	1.0	1.1	1.2
F	0.7	0.8	0.9
G	0.3	0.4	0.5
Н	0.9	1.0	1.1
М	0.7	0.8	0.9

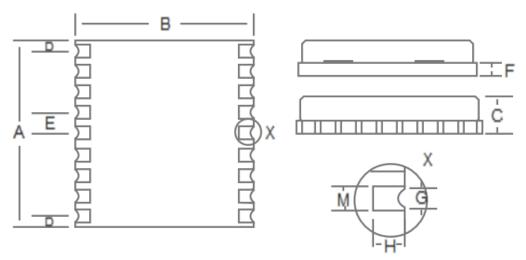


Figure 3-1 Mechanical Layout

# 3.4 Pin Definition (Top View)

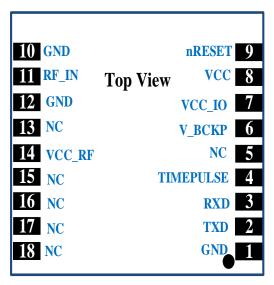


Figure 3-2 UM220-IV M0

No	Name	I/O	Electrical level	Description
1	GND	I		Ground
2	TXD	0	LVTTL	UART 1-TX
3	RXD	I	LVTTL	UART 1-RX
4	TIMEPULSE	0	LVTTL	1PPS
5	NC	I	LVTTL	Reserve
6	V_BCKP	I	1.65V~3.6V	Voltage for RTC. If you do not use the hot start function, connect V_BCKP to VCC. Do NOT connect it to ground or leave it floating.
7	VCC_IO	I	3.0V~3.6V	GPIO power supply
8	VCC	I	3.0V~3.6V	Main power
9	nRESET	I	LVTTL	For reset, Low level active, if you do not use the pin, please leave it hanging
10	GND	I		Ground
11	RF_IN	I		GNSS signal input (BDS B1+GPS L1)
12	GND	I		Ground
13	NC	0		Reserve
14	VCC_RF⁴	0	=VCC	Output voltage RF section
15	NC	1/0		Reserve
16	NC	I/O		Reserve

<sup>&</sup>lt;sup>4</sup> VCC\_RF does not have short circuit detection function;

-



No	Name	I/O	Electrical level	Description
17	NC	I/O		Reserve
18	NC	I/O		Reserve

## 4 Hardware Design

### 4.1 Design in Considerations

To make UM220-IV M0 work normally, you need to properly connect the following:

- > Connect all the GND pins to ground.
- $\triangleright$  Connect the RF\_IN signal to the antenna, and the line will keep 50Ω impedance matching.
- > Ensure COM1 is connected to a PC or an external processor, users can use this serial port to receive position data. COM1 is also necessary for firmware upgrades.

In order to obtain good performance, special concern should be paid during the design:

- Power supply: Stable and low ripple power is necessary for good performance.
  Make sure the peak to peak voltage ripple does not exceed 50mV.
  - Use LDO to ensure the purity of power supply
  - Try to place LDO close to the module in layout
  - Widen the power circuit or use copper pour surface to transmit current
  - Avoid walking through any high-power or high inductance devices such as a magnetic coil
- ➤ UART interfaces: Ensure that the signals and baud rate of main equipment match that of UM220-IV M0 module
- Antenna interface: Make sure the antenna impedance matches, and the cable is short without any kinks, try to avoid acute angles
- ➤ Antenna position: In order to ensure a good signal-to-noise ratio, the antenna should be well isolated from any electromagnetic radiation source, especially an electromagnetic radiation in the frequency range of 1559 ~ 1605MHz
- > Try to avoid designing in any circuits underneath UM220-IV M0
- > This module is a temperature sensitive device. Dramatic changes in temperature will result in reduced performance, so keep it away as far as possible from any

high-power high-temperature air and heating devices.

## 4.2 Power Supply Requirements

### 4.2.1 Main Supply (VCC)

The voltage range of VCC is  $3.0 \text{ V} \sim 3.6 \text{ V}$ .

#### Notes:

- The VCC initial level when power-on should be less than 0.4 V.
- The VCC ramp when power-on should be monotonic, without plateaus.
- The voltages of undershoot and ringing should be within 5% VCC.
- VCC power-on waveform: The time interval from 10% rising to 90% must be within  $100 \ \mu s \sim 10 \ ms$ .
- Power-on time interval: The time interval between the power-off (VCC < 0.4 V) to the next power-on is recommended to be larger than 500 ms.

### 4.2.2 Backup Supply (V\_BCKP)

If the hot start function is needed, users should supply backup power to the module. The voltage range of V\_BCKP is  $1.65 \text{ V} \sim 3.6 \text{ V}$ .

#### Notes:

- The V\_BCKP initial level when power-on should be less than 0.4 V.
- The V\_BCKP ramp when power-on should be monotonic, without plateaus.
- The voltages of undershoot and ringing should be within 5% V\_BCKP.
- V\_BCKP power-on waveform: The time interval from 10% rising to 90% must be within 100  $\mu$ s  $\sim$  10 ms.
- Power-on time interval: The time interval between the power-off (V\_BCKP < 0.4 V)</li>
   to the next power-on is recommended to be larger than 500 ms.
- The V\_BCKP pin cannot be floating or connected to ground. When V\_BCKP is not used, it should be connected to VCC or connected to backup power.

### 4.3 Avoid Leakage Power

The module input ports of UM220-IV M0 include: RXD and GPIO. When the module is not powered on, if there is data input in the above ports, it will form a series of power on the module VCC. When the series voltage is higher than 1.6V, it may cause a failure of starting up when the module is powered on.



#### Solution:

When the module is not powered on, make sure that the IO port connected to the module is in a high-resistance state or a low level to avoid leakage power. Another solution is to connect a  $1K\Omega$  resistor in series to the serial port RX, and connect a  $33\Omega$  or  $1K\Omega$  resistor in series to TX (There is no need to connect any resistor to the TX of the module with PN 2310408000024). It is also recommended to connect a  $4.7K\Omega$  resistor in series to the Pin of other necessary PIOs.

#### 4.4 Antenna

If the UM220-IV M0 uses an active antenna, the bias voltage V\_BIAS is supplied to the antenna through a feed inductor. It's recommended to use an independent power as V\_BIAS to supply the antenna.

If the antenna power supply and the module's main supply VCC use the same power rail, the ESD, surge and overvoltage from the antenna will have an effect on VCC, which may cause damage to the module. Therefore, it's recommended to design an independent power rail for the antenna to reduce the possibility of damage to the module.

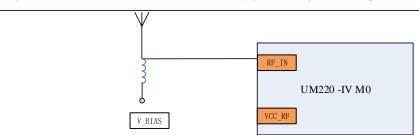


Figure 4-1 UM220-IV M0 Active Antenna Solution

If UM220-IV M0 uses a passive antenna, the antenna can be directly connected to the RF\_IN pin. It should be noted that the use of passive antennas may cause a decrease in GNSS performance compared to active antennas.

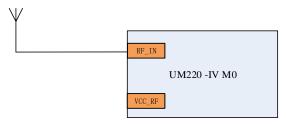


Figure 4-2 UM220-IV M0 Passive Antenna Solution

### 4.5 Reset

If the reset pin nRESET of UM220-IV M0 module needs to be used, the following timing requirements must be met between the nRESET and the power supply VCC. During normal operation of the module, pulling down the nRESET pin over 5 ms can also reset the module.

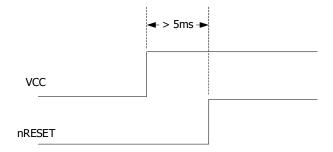


Figure 4-3 UM220-IV M0 Reset Requirement

### 4.6 Serial Port

UM220-IV M0 has one LVTTL serial port, for PC connection, please use a RS232 voltage level converter.

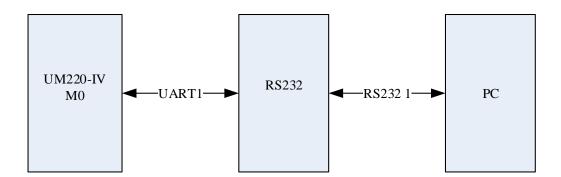


Figure 4-4 Connect COM to PC

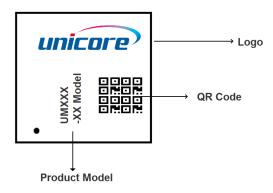


## 5 Disassembly

When it is necessary to remove the module, it is recommended to melt the soldering tin of the pins on both sides of the module with an electric soldering iron and remove the module with tweezers. Do not use other means to remove the module (such as using a hot air gun to blow the module), may lead to module damage.

# 6 Package

### 6.1 Product Label Description



### 6.2 Package Description

The UM220-IV M0 modules are packaged in vacuum sealed aluminum foil anti-static bags with desiccant and moisture-proof agent. When using reflow welding process to weld modules, please strictly comply with IPC standard to conduct humidity control on modules. As packaging materials such as carrier belt can only withstand the temperature of 65 degrees Celsius, modules shall be removed from the packaging during baking.



Figure 6-1 UM220 package

Item	Description
Module	1000 pics/reel
Reel Size	Workpiece tray: 13" External diameter 330mm, internal diameter 100mm, width 24mm, thickness 2.0mm
Carrier Tape	Space between: 20mm

Check the humidity indicator card before soldering. The 30% indication is blue under normal conditions, as shown in Figure 6-2. Bake modules firstly before soldering if the 30% indication turns pink, as shown in Figure 6-3. The UM220-IV M0 modules are rated at MSL level 3, for more MSL information, please refer to www.jedec.org.

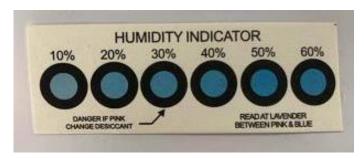


Figure 6-2 the 30% indication is blue



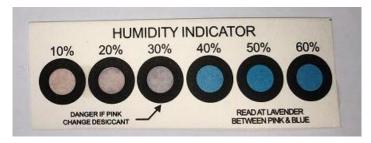


Figure 6-3 the 30% indication is pink

The shelf life of UM220-IV M0 is one year.

### 7 Clean

Do not use alcohol or other organic solvents to clean, or it may lead to flux residues flooding into the shielding shell, causing mildew and other problems.

# 8 Reflow Soldering

In order to avoid device falling off, the module should be placed on the top of the main board during welding. Reflow soldering temperature curve is recommended as shown in Figure 8-1 below (M705-GRN360 is recommended for solder paste). Note: the module can only be welded once.

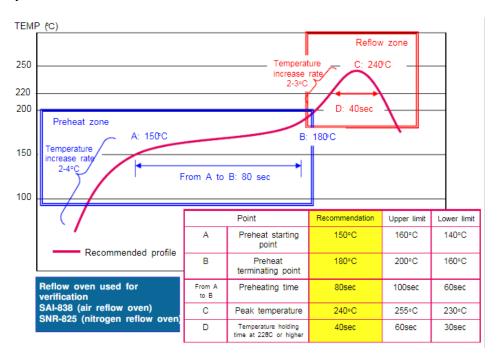


Figure 8-1 Reflow Soldering Line

**Note:** The apertures in the stencil need to meet the customer's own design requirements and inspection specifications, and the thickness of the stencil should be above 0.15mm, and 0.18mm is recommended.

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